

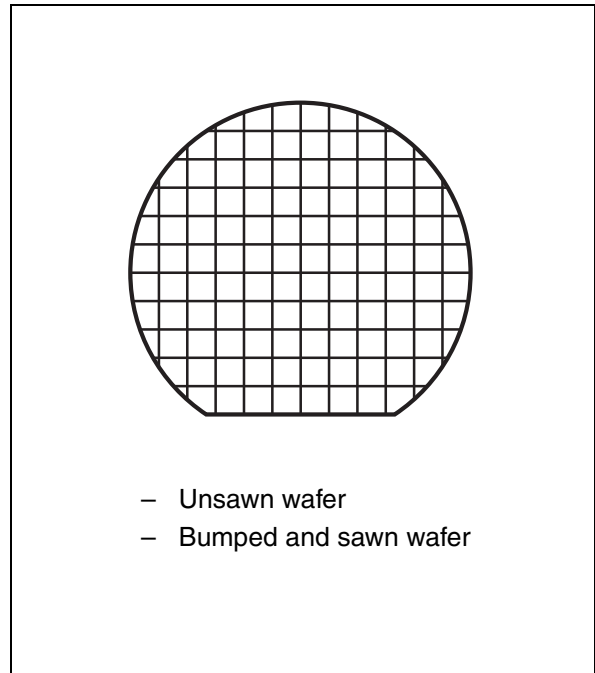
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**13.56 MHz short-range contactless memory chip  
with 2048-bit EEPROM and anticollision functions**

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**Features**

- ISO 14443-2 Type B air interface compliant
- ISO 14443-3 Type B frame format compliant
- 13.56 MHz carrier frequency
- 847 kHz subcarrier frequency
- 106 Kbit/second data transfer
- 8 bit Chip\_ID based anticollision system
- 2 count-down binary counters with automated antitearing protection
- 64-bit Unique Identifier
- 2048-bit EEPROM with Write Protect feature
- Read\_block and Write\_block (32 bits)
- Internal tuning capacitor
- 1million erase/write cycles
- 40-year data retention
- Self-timed programming cycle
- 5 ms typical programming time



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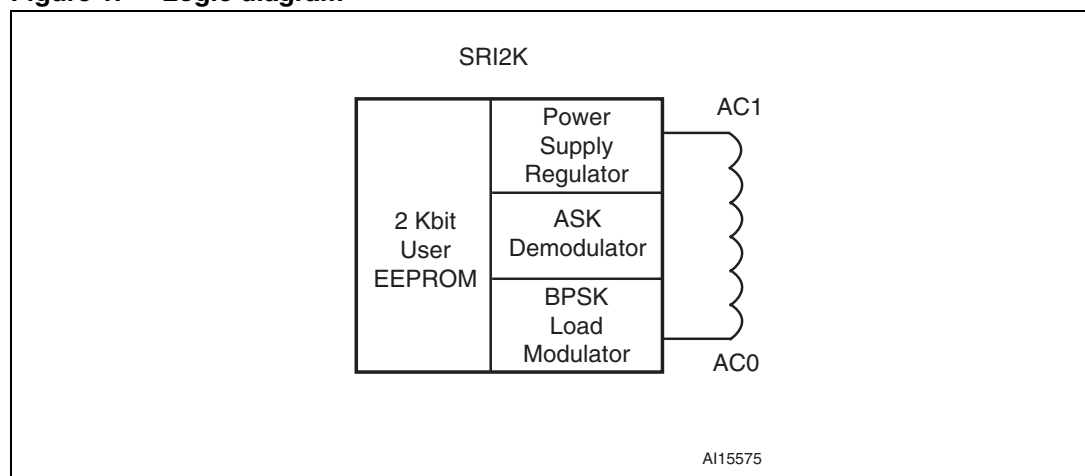
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# 1 Description

The SRI2K is a contactless memory, powered by an externally transmitted radio wave. It contains a 2048-bit user EEPROM. The memory is organized as 64 blocks of 32 bits. The SRI2K is accessed via the 13.56 MHz carrier. Incoming data are demodulated and decoded from the received amplitude shift keying (ASK) modulation signal and outgoing data are generated by load variation using bit phase shift keying (BPSK) coding of a 847 kHz subcarrier. The received ASK wave is 10% modulated. The data transfer rate between the SRI2K and the reader is 106 kbit/s in both reception and emission modes.

The SRI2K follows the ISO 14443 part 2 type B recommendation for the radio-frequency power and signal interface.

**Figure 1. Logic diagram**



The SRI2K is specifically designed for short range applications that need re-usable products. The SRI2K includes an anticollision mechanism that allows it to detect and select tags present at the same time within range of the reader. The anticollision is based on a probabilistic scanning method using slot markers. Using the STMicroelectronics single chip coupler, CRX14, it is easy to design a reader and build a contactless system.

**Table 1. Signal names**

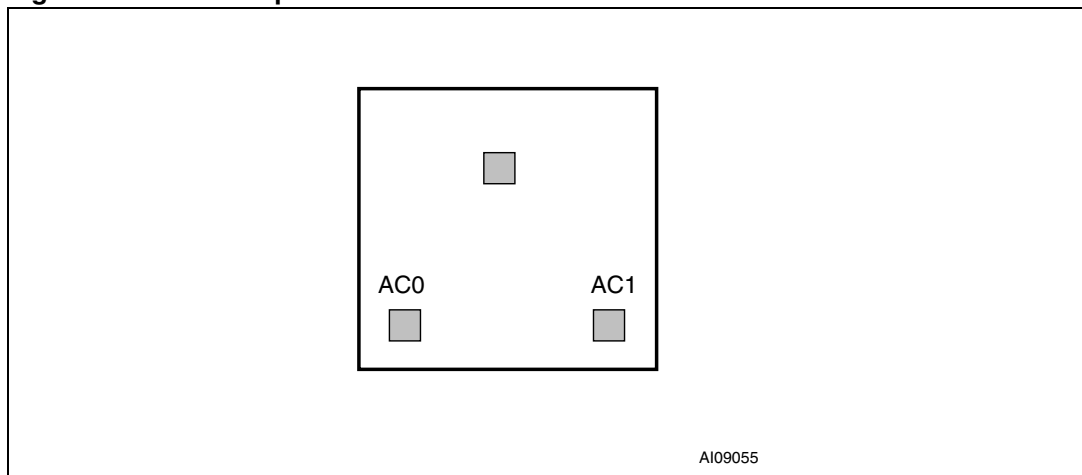
Signal names	Description
AC1	Antenna coil
AC0	Antenna coil

The SRI2K contactless EEPROM can be randomly read and written in block mode (each block containing 32 bits). The instruction set includes the following nine commands:

- Read\_block
- Write\_block
- Initiate
- Pcall16
- Slot\_marker
- Select
- Completion
- Reset\_to\_inventory
- Get\_UID

The SRI2K memory is organized in three areas, as described in [Figure 3](#). The first area is a resettable OTP (one time programmable) area in which bits can only be switched from 1 to 0. Using a special command, it is possible to erase all bits of this area to 1. The second area provides two 32-bit binary counters which can only be decremented from FFFF FFFFh to 0000 0000h, and gives a capacity of 4,294,967,296 units per counter. The last area is the EEPROM memory. It is accessible by block of 32 bits and includes an auto-erase cycle during each Write\_block command.

**Figure 2. Die floor plan**



## 2 Signal description

### 2.1 AC1, AC0

The pads for the Antenna Coil. AC1 and AC0 must be directly bonded to the antenna.

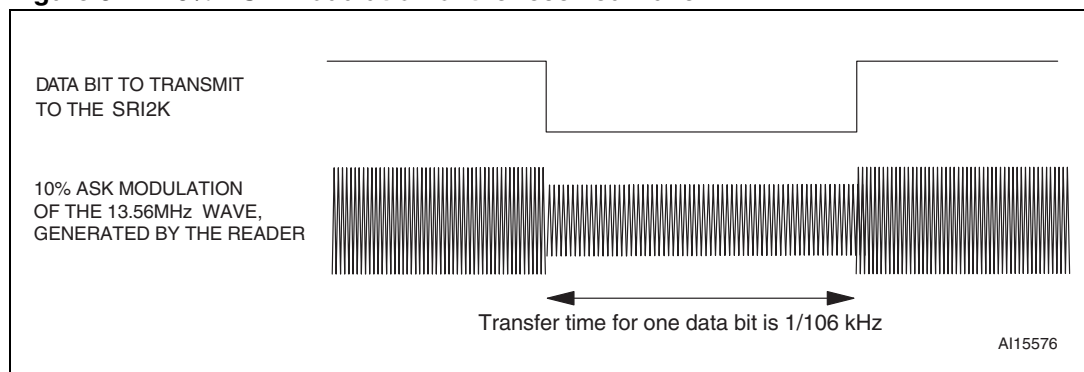


### 3 Data transfer

#### 3.1 Input data transfer from the reader to the SRI2K (request frame)

The reader must generate a 13.56 MHz sinusoidal carrier frequency at its antenna, with enough energy to “remote-power” the memory. The energy received at the SRI2K’s antenna is transformed into a supply voltage by a regulator, and into data bits by the ASK demodulator. For the SRI2K to decode correctly the information it receives, the reader must 10% amplitude-modulate the 13.56 MHz wave before sending it to the SRI2K. This is represented in *Figure 3*. The data transfer rate is 106 Kbits/s.

**Figure 3. 10% ASK modulation of the received wave**

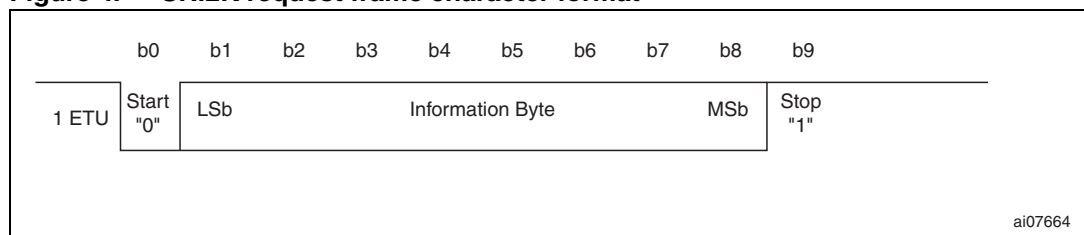


##### 3.1.1 Character transmission format for request frame

The SRI2K transmits and receives data bytes as 10-bit characters, with the least significant bit ( $b_0$ ) transmitted first, as shown in *Figure 4*. Each bit duration, an ETU (elementary time unit), is equal to 9.44  $\mu$ s (1/106 kHz).

These characters, framed by a start of frame (SOF) and an end of frame (EOF), are put together to form a command frame as shown in *Figure 10*. A frame includes an SOF, commands, addresses, data, a CRC and an EOF as defined in the ISO 14443-3 Type B Standard. If an error is detected during data transfer, the SRI2K does not execute the command, but it does not generate an error frame.

**Figure 4. SRI2K request frame character format**



**Table 2. Bit description**

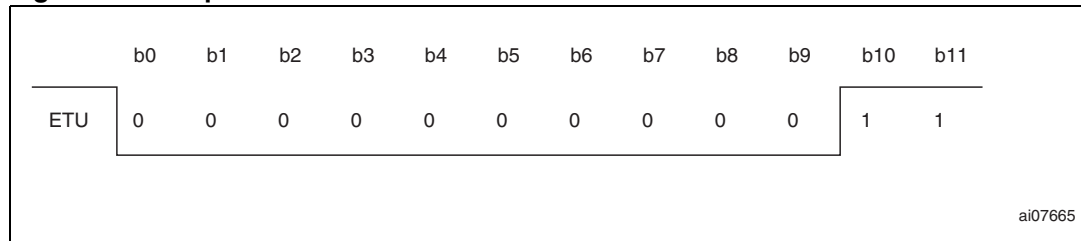
Bit	Description	Value
b <sub>0</sub>	Start bit used to synchronize the transmission	b <sub>0</sub> = 0
b <sub>1</sub> to b <sub>8</sub>	Information byte (command, address or data)	The information byte is sent with the least significant bit first
b <sub>9</sub>	Stop bit used to indicate the end of a character	b <sub>9</sub> = 1

### 3.1.2 Request start of frame

The SOF described in [Figure 5](#) is composed of:

- one falling edge,
- followed by 10 ETUs at logic-0,
- followed by a single rising edge,
- followed by at least 2 ETUs (and at most 3) at logic-1.

**Figure 5. Request start of frame**

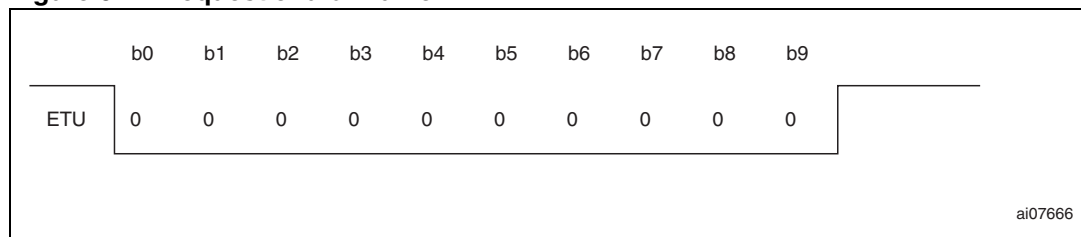


### 3.1.3 Request end of frame

The EOF shown in [Figure 6](#) is composed of:

- one falling edge,
- followed by 10 ETUs at logic-0,
- followed by a single rising edge.

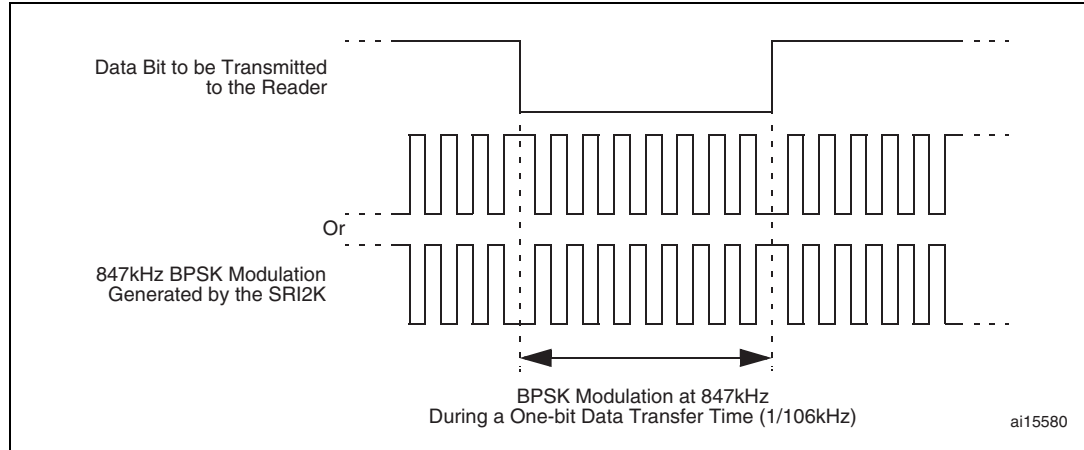
**Figure 6. Request end of frame**



### 3.2 Output data transfer from the SRI2K to the reader (answer frame)

The data bits issued by the SRI2K use backscattering. Backscattering is obtained by modifying the SRI2K current consumption at the antenna (load modulation). The load modulation causes a variation at the reader antenna by inductive coupling. With appropriate detector circuitry, the reader is able to pick up information from the SRI2K. To improve load-modulation detection, data is transmitted using a BPSK encoded, 847 kHz subcarrier frequency  $f_s$  as shown in *Figure 7*, and as specified in the ISO 14443-2 Type B Standard.

**Figure 7. Wave transmitted using BPSK subcarrier modulation**



#### 3.2.1 Character transmission format for answer frame

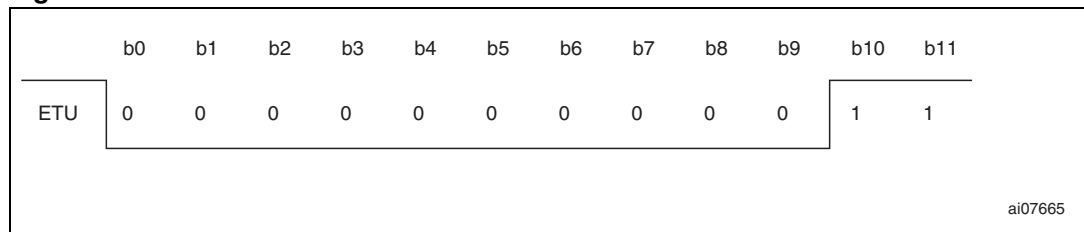
The character format is the same as for input data transfer (*Figure 4*). The transmitted frames are made up of an SOF, data, a CRC and an EOF (*Figure 10*). As with an input data transfer, if an error occurs, the reader does not issue an error code to the SRI2K, but it should be able to detect it and manage the situation. The data transfer rate is 106 Kbits/second.

#### 3.2.2 Answer start of frame

The SOF described in *Figure 8* is composed of:

- followed by 10 ETUs at logic-0
- followed by 2 ETUs at logic-1

**Figure 8. Answer start of frame**

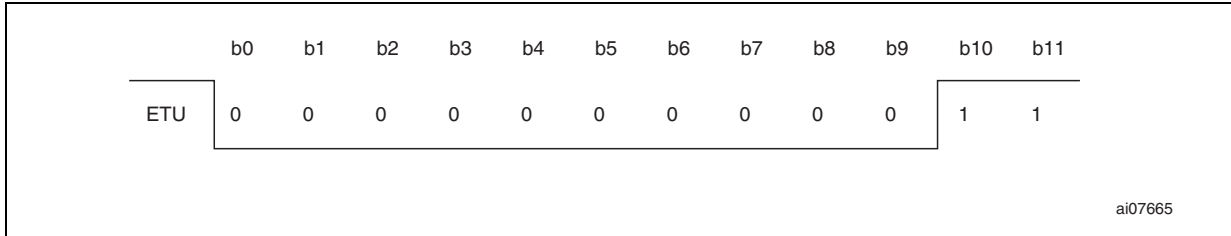


### 3.2.3 Answer end of frame

The EOF shown in *Figure 9* is composed of:

- followed by 10 ETUs at logic-0,
- followed by 2 ETUs at logic-1.

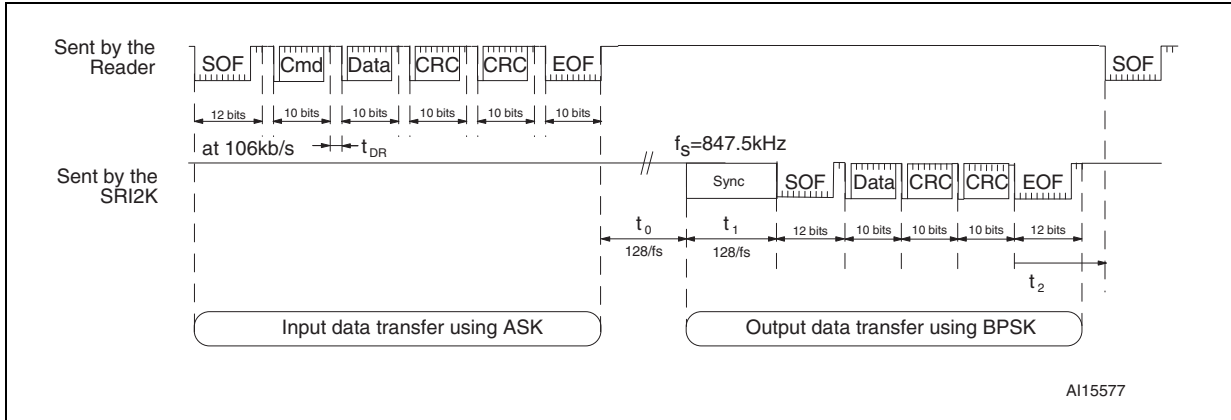
**Figure 9. Answer end of frame**



### 3.3 Transmission frame

Between the request data transfer and the answer data transfer, all ASK and BPSK modulations are suspended for a minimum time of  $t_0 = 128/f_S$ . This delay allows the reader to switch from Transmission to Reception mode. It is repeated after each frame. After  $t_0$ , the 13.5 6MHz carrier frequency is modulated by the SRI2K at 847 kHz for a period of  $t_1 = 128/f_S$  to allow the reader to synchronize. After  $t_1$ , the first phase transition generated by the SRI2K forms the start bit ('0') of the answer SOF. After the falling edge of the answer EOF, the reader waits a minimum time,  $t_2$ , before sending a new request frame to the SRI2K.

**Figure 10. Example of a complete transmission frame**



### 3.4 CRC

The 16-bit CRC used by the SRI2K is generated in compliance with the ISO14443 Type B recommendation. For further information, please see [Appendix A](#). The initial register contents are all 1s: FFFFh.

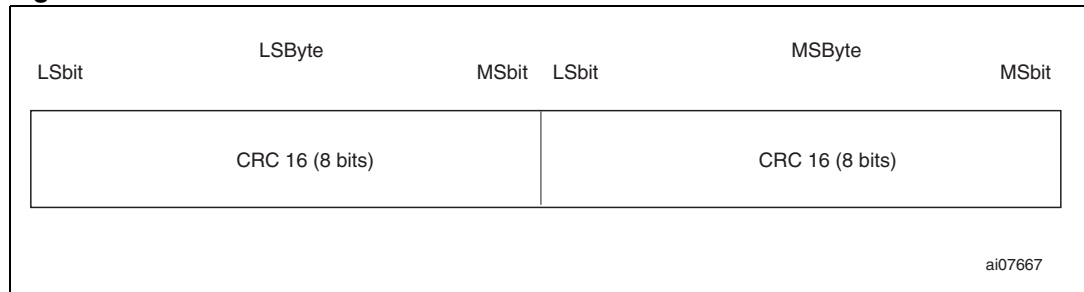
The two-byte CRC is present in every request and in every answer frame, before the EOF. The CRC is calculated on all the bytes between SOF (not included) and the CRC field.

Upon reception of a request from a reader, the SRI2K verifies that the CRC value is valid. If it is invalid, the SRI2K discards the frame and does not answer the reader.

Upon reception of an answer from the SRI2K, the reader should verify the validity of the CRC. In case of error, the actions to be taken are the reader designer's responsibility.

The CRC is transmitted with the least significant byte first and each byte is transmitted with the least significant bit first.

**Figure 11. CRC transmission rules**



## 4 Memory mapping

The SRI2K is organized as 64 blocks of 32 bits as shown in [Table 3](#). All blocks are accessible by the Read\_block command. Depending on the write access, they can be updated by the Write\_block command. A Write\_block updates all the 32 bits of the block.

**Table 3. SRI2K memory mapping**

Block Addr	MSB b <sub>31</sub>	32-bit block			LSB b <sub>0</sub>	Description
		b <sub>24</sub> b <sub>23</sub>	b <sub>16</sub> b <sub>15</sub>	b <sub>8</sub> b <sub>7</sub>		
0		32 bits Boolean area				Resettable OTP bits
1		32 bits Boolean area				
2		32 bits Boolean area				
3		32 bits Boolean area				
4		32 bits Boolean area				
5		32 bits binary counter				Count down counter
6		32 bits binary counter				
7		User area				Lockable EEPROM
8		User area				
9		User area				
10		User area				
11		User area				
12		User area				
13		User area				
14		User area				
15		User area				
16		User area				
...		User area				EEPROM
63		User area				
255	OTP_Lock_Reg	ST Reserved		Fixed Chip_ID (Option)	System OTP bits	
UID0	64 bits UID area				ROM	
UID1						

### 4.1 Resettable OTP area

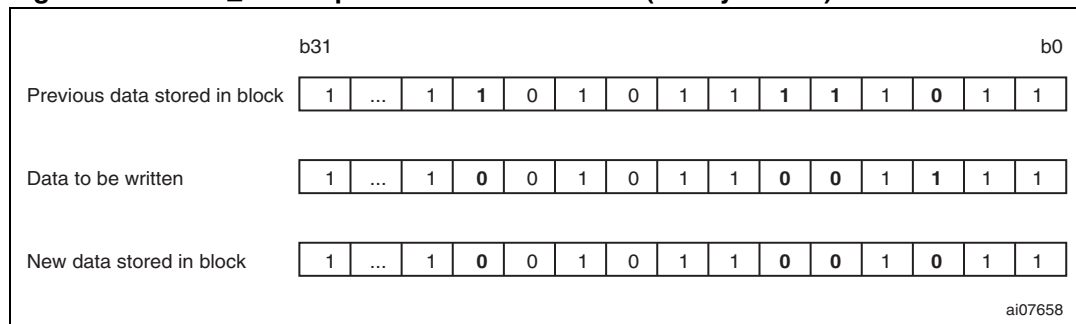
In this area contains five individual 32-bit Boolean words (see [Figure 12](#) for a map of the area). A Write\_block command will not erase the previous contents of the block as the write cycle is not preceded by an auto-erase cycle. This feature can be used to reset selected bits from 1 to 0. All bits previously at 0 remain unchanged. When the 32 bits of a block are all at 0, the block is empty, and cannot be updated any more. See [Figure 13](#) and [Figure 14](#) for examples of the result of the Write\_block command in the resettable OTP area.

**Figure 12. Resettable OTP area (addresses 0 to 4)**

Block address	MSb b31	b24 b23	32-bit block b16 b15	b8 b7	LSb b0	Description
0			32-bit Boolean area			Resettable OTP bit
1			32-bit Boolean area			
2			32-bit Boolean area			
3			32-bit Boolean area			
4			32-bit Boolean area			

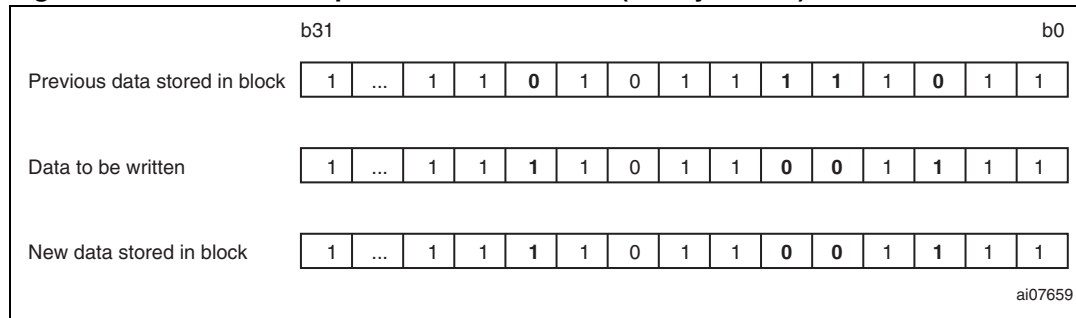
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**Figure 13. Write\_block update in Standard mode (binary format)**



The five 32-bit blocks making up the resettable OTP area can be erased in one go by adding an auto-erase cycle to the Write\_block command. An auto-erase cycle is added each time the SRI2K detects a Reload command. The Reload command is implemented through a specific update of the 32-bit binary counter located at block address 6 (see [“Section 4.2: 32-bit binary counters”](#) for details).

**Figure 14. Write\_block update in Reload mode (binary format)**



## 4.2 32-bit binary counters

The two 32-bit binary counters located at block addresses 5 and 6, respectively, are used to count down from  $2^{32}$  (4096 million) to 0. The SRI2K uses dedicated logic that only allows the update of a counter if the new value is lower than the previous one. This feature allows the application to count down by steps of 1 or more. The initial value in Counter 5 is FFFF FFFEh and is FFFF FFFFh in Counter 6. When the value displayed is 0000 0000h, the counter is empty and cannot be reloaded. The counter is updated by issuing the Write\_block command to block address 5 or 6, depending on which counter is to be updated. The Write\_block command writes the new 32-bit value to the counter block address. *Figure 16* shows examples of how the counters operate.

The counter programming cycles are protected by automated antitearing logic. This function allows the counter value to be protected in case of power down within the programming cycle. In case of power down, the counter value is not updated and the previous value continues to be stored.

**Figure 15. Binary counter (addresses 5 to 6)**

Block Address	MSb b31	b24 b23	32-bit block b16 b15	b8 b7	LSb b0	Description
5	32-bit binary counter					Count down Counter
6	32-bit binary counter					

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**Figure 16. Countdown example (binary format)**

	b31											b0		
Initial data	1	...	1	1	1	1	1	1	1	1	1	1	1	1
1-unit decrement	1	...	1	1	1	1	1	1	1	1	1	1	1	0
1-unit decrement	1	...	1	1	1	1	1	1	1	1	1	1	0	1
1-unit decrement	1	...	1	1	1	1	1	1	1	1	1	1	0	0
8-unit decrement	1	...	1	1	1	1	1	1	1	1	0	1	0	0
Increment not allowed	1	...	1	1	1	1	1	1	1	1	1	0	0	0

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The counter with block address 6 controls the Reload command used to reset the resettable OTP area (addresses 0 to 4). Bits  $b_{31}$  to  $b_{21}$  act as an 11-bit Reload counter; whenever one of these 11 bits is updated, the SRI2K detects the change and adds an Erase cycle to the Write\_block command for locations 0 to 4 (see the “*Resettable OTP area*” paragraph). The Erase cycle remains active until a Power-off or a Select command is issued. The SRI2K’s resettable OTP area can be reloaded up to 2 047 times ( $2^{11}-1$ ).



### 4.3 EEPROM area

The 57 blocks between addresses 7 and 63 are EEPROM blocks of 32 bits each (228 bytes in total). (See [Figure 17](#) for a map of the area.) These blocks can be accessed using the Read\_block and Write\_block commands. The Write\_block command for the EEPROM area always includes an auto-erase cycle prior to the write cycle.

Blocks 7 to 15 can be write-protected. Write access is controlled by the 8 bits of the OTP\_Lock\_Reg located at block address 255 (see "[OTP\\_Lock\\_Reg](#)" for details). Once protected, these blocks (7 to 15) cannot be unprotected.

**Figure 17. EEPROM (addresses 7 to 63)**

Block Address	MSb b31	b24 b23	32-bit Block b16 b15	b8 b7	LSb b0	Description
7			User Area			Lockable EEPROM
8			User Area			
9			User Area			
10			User Area			
11			User Area			
12			User Area			
13			User Area			
14			User Area			
15			User Area			
16			User Area			EEPROM
...			User Area			
63			User Area			

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### 4.4 System area

This area is used to modify the settings of the SRI2K. It contains 3 registers: OTP\_Lock\_Reg, Fixed Chip\_ID and ST Reserved. See [Figure 18](#) for a map of this area.

A Write\_block command in this area will not erase the previous contents. Selected bits can thus be set from 1 to 0. All bits previously at 0 remain unchanged. Once all the 32 bits of a block are at 0, the block is empty and cannot be updated any more.

Figure 18. System area

Block address	MSb b31	b24 b23	32-bit block b16 b15	b8 b7	LSb b0	Description
255	OTP_Lock_Reg		ST reserved	Fixed Chip_ID (Option)		OTP

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#### 4.4.1 OTP\_Lock\_Reg

The 8 bits,  $b_{31}$  to  $b_{24}$ , of the System area (block address 255) are used as OTP\_Lock\_Reg bits in the SRI2K. They control the write access to the 9 EEPROM blocks with addresses 7 to 15 as follows:

- When  $b_{24}$  is at 0, blocks 7 and 8 are write-protected
- When  $b_{25}$  is at 0, block 9 is write-protected
- When  $b_{26}$  is at 0, block 10 is write-protected
- When  $b_{27}$  is at 0, block 11 is write-protected
- When  $b_{28}$  is at 0, block 12 is write-protected
- When  $b_{29}$  is at 0, block 13 is write-protected
- When  $b_{30}$  is at 0, block 14 is write-protected
- When  $b_{31}$  is at 0, block 15 is write-protected.

The OTP\_Lock\_Reg bits cannot be erased. Once write-protected, EEPROM blocks behave like ROM blocks and cannot be unprotected.

#### 4.4.2 Fixed Chip\_ID (Option)

The SRI2K is provided with an anticollision feature based on a random 8-bit Chip\_ID. Prior to selecting an SRI2K, an anticollision sequence has to be run to search for the Chip\_ID of the SRI2K. This is a very flexible feature, however the searching loop requires time to run.

For some applications, much time could be saved by knowing the value of the SRI2K Chip\_ID beforehand, so that the SRI2K can be identified and selected directly without having to run an anticollision sequence. This is why the SRI2K was designed with an optional mask setting used to program a fixed 8-bit Chip\_ID to bits  $b_7$  to  $b_0$  of the system area. When the fixed Chip\_ID option is used, the random Chip\_ID function is disabled.

## 5 SRI2K operation

All commands, data and CRC are transmitted to the SRI2K as 10-bit characters using ASK modulation. The start bit of the 10 bits,  $b_0$ , is sent first. The command frame received by the SRI2K at the antenna is demodulated by the 10% ASK demodulator, and decoded by the internal logic. Prior to any operation, the SRI2K must have been selected by a Select command. Each frame transmitted to the SRI2K must start with a start of frame, followed by one or more data characters, two CRC bytes and the final end of frame. When an invalid frame is decoded by the SRI2K (wrong command or CRC error), the memory does not return any error code.

When a valid frame is received, the SRI2K may have to return data to the reader. In this case, data is returned using BPSK encoding, in the form of 10-bit characters framed by an SOF and an EOF. The transfer is ended by the SRI2K sending the 2 CRC bytes and the EOF.

## 6 SRI2K states

The SRI2K can be switched into different states. Depending on the current state of the SRI2K, its logic will only answer to specific commands. These states are mainly used during the anticollision sequence, to identify and to access the SRI2K in a very short time. The SRI2K provides 6 different states, as described in the following paragraphs and in [Figure 19](#).

### 6.1 Power-off state

The SRI2K is in Power-off state when the electromagnetic field around the tag is not strong enough. In this state, the SRI2K does not respond to any command.

### 6.2 Ready state

When the electromagnetic field is strong enough, the SRI2K enters the Ready state. After Power-up, the Chip\_ID is initialized with a random value. The whole logic is reset and remains in this state until an Initiate() command is issued. Any other command will be ignored by the SRI2K.

### 6.3 Inventory state

The SRI2K switches from the Ready to the Inventory state after an Initiate() command has been issued. In Inventory state, the SRI2K will respond to any anticollision commands: Initiate(), Pcall16() and Slot\_marker(), and then remain in the Inventory state. It will switch to the Selected state after a Select(Chip\_ID) command is issued, if the Chip\_ID in the command matches its own. If not, it will remain in Inventory state.

### 6.4 Selected state

In Selected state, the SRI2K is active and responds to all Read\_block(), Write\_block() and Get\_UID() commands. When an SRI2K has entered the Selected state, it no longer responds to anticollision commands. So that the reader can access another tag, the SRI2K can be switched to the Deselected state by sending a Select(Chip\_ID2) with a Chip\_ID that does not match its own, or it can be placed in Deactivated state by issuing a Completion() command. Only one SRI2K can be in Selected state at a time.

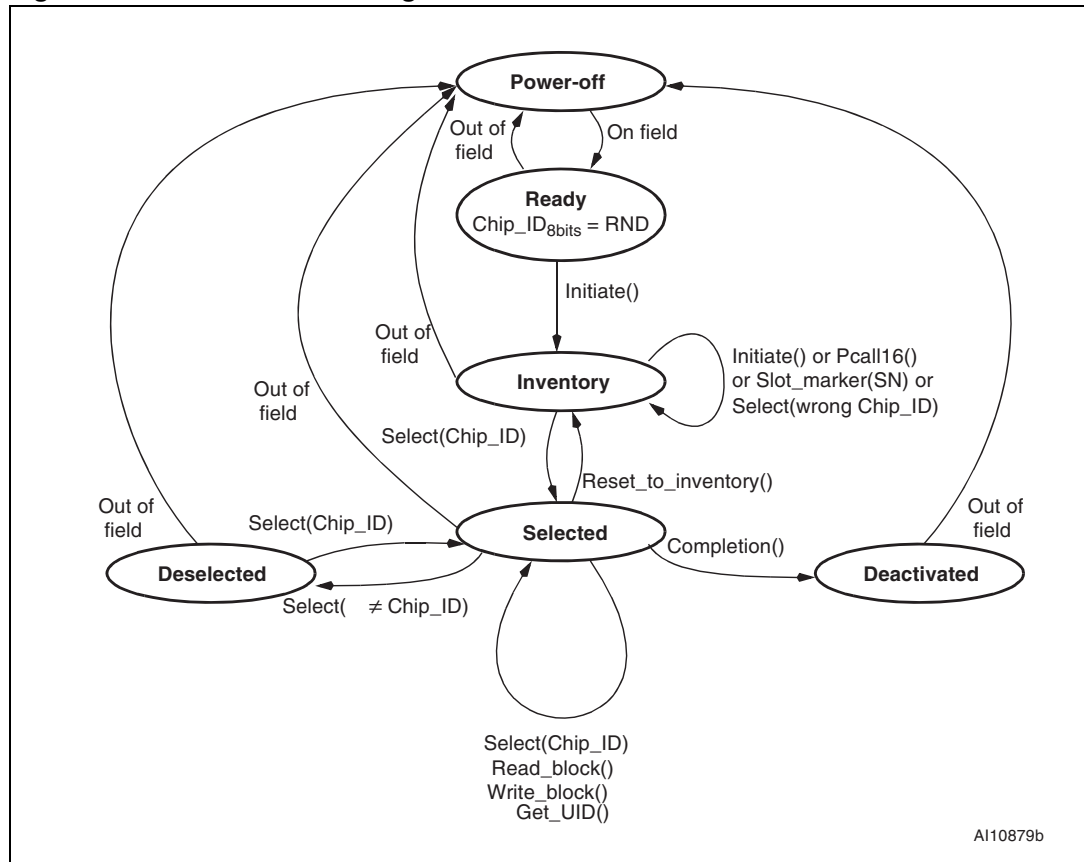
### 6.5 Deselected state

Once the SRI2K is in Deselected state, only a Select(Chip\_ID) command with a Chip\_ID matching its own can switch it back to Selected state. All other commands are ignored.

### 6.6 Deactivated state

When in this state, the SRI2K can only be turned off. All commands are ignored.

Figure 19. State transition diagram



## 7 Anticollision

The SRI2K provides an anticollision mechanism that searches for the Chip\_ID of each device that is present in the reader field range. When known, the Chip\_ID is used to select an SRI2K individually, and access its memory. The anticollision sequence is managed by the reader through a set of commands described in [Section 5: SRI2K operation](#):

- Initiate()
- Pcall16()
- Slot\_marker().

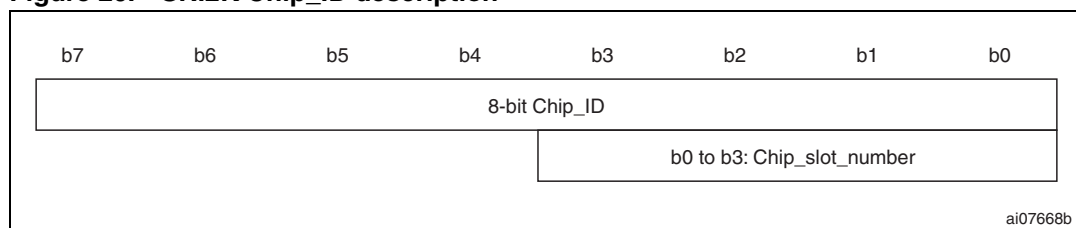
The reader is the master of the communication with one or more SRI2K device(s). It initiates the tag communication activity by issuing an Initiate(), Pcall16() or Slot\_marker() command to prompt the SRI2K to answer. During the anticollision sequence, it might happen that two or more SRI2K devices respond simultaneously, so causing a collision. The command set allows the reader to handle the sequence, to separate SRI2K transmissions into different time slots. Once the anticollision sequence has completed, SRI2K communication is fully under the control of the reader, allowing only one SRI2K to transmit at a time.

The Anticollision scheme is based on the definition of time slots during which the SRI2K devices are invited to answer with minimum identification data: the Chip\_ID. The number of slots is fixed at 16 for the Pcall16() command. For the Initiate() command, there is no slot and the SRI2K answers after the command is issued. SRI2K devices are allowed to answer only once during the anticollision sequence. Consequently, even if there are several SRI2K devices present in the reader field, there will probably be a slot in which only one SRI2K answers, allowing the reader to capture its Chip\_ID. Using the Chip\_ID, the reader can then establish a communication channel with the identified SRI2K. The purpose of the anticollision sequence is to allow the reader to select one SRI2K at a time.

The SRI2K is given an 8-bit Chip\_ID value used by the reader to select only one among up to 256 tags present within its field range. The Chip\_ID is initialized with a random value during the Ready state, or after an Initiate() command in the Inventory state.

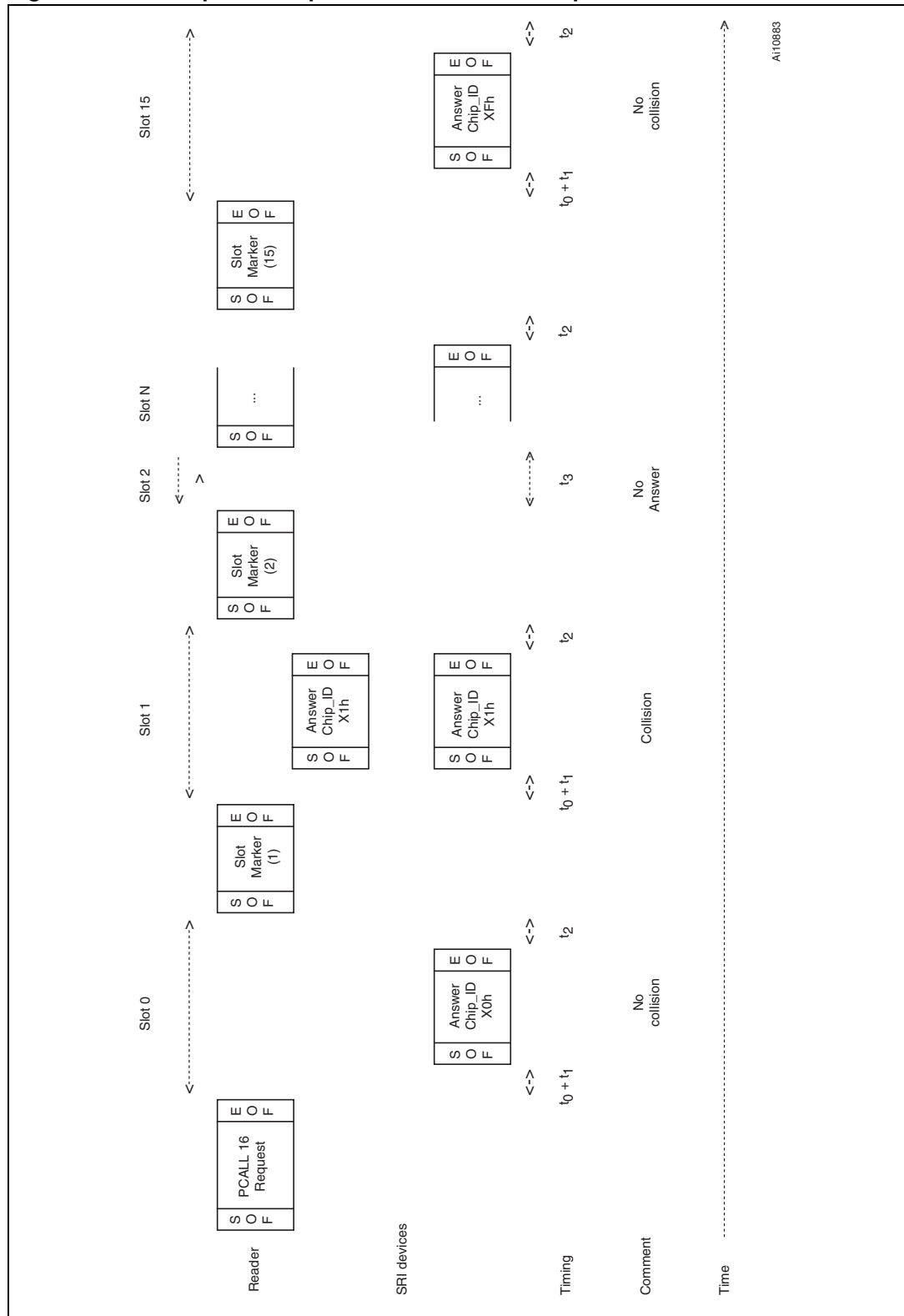
The four least significant bits (b<sub>0</sub> to b<sub>3</sub>) of the Chip\_ID are also known as the Chip\_slot\_number. This 4-bit value is used by the Pcall16() and Slot\_marker() commands during the anticollision sequence in the Inventory state.

**Figure 20. SRI2K Chip\_ID description**



Each time the SRI2K receives a Pcall16() command, the Chip\_slot\_number is given a new 4-bit random value. If the new value is 0000<sub>b</sub>, the SRI2K returns its whole 8-bit Chip\_ID in its answer to the Pcall16() command. The Pcall16() command is also used to define the slot number 0 of the anticollision sequence. When the SRI2K receives the Slot\_marker (SN) command, it compares its Chip\_slot\_number with the Slot\_number parameter (SN). If they match, the SRI2K returns its Chip\_ID as a response to the command. If they do not, the SRI2K does not answer. The Slot\_marker(SN) command is used to define all the anticollision slot numbers from 1 to 15.

Figure 21. Description of a possible anticollision sequence



1. The value X in the answer Chip\_ID means a random hexadecimal character from 0 to F.

## 7.1 Description of an anticollision sequence

The anticollision sequence is initiated by the Initiate() command which triggers all the SRI2K devices that are present in the reader field range, and that are in Inventory state. Only SRI2K devices in Inventory state will respond to the Pcall16() and Slot\_marker(SN) anticollision commands.

A new SRI2K introduced in the field range during the anticollision sequence will not be taken into account as it will not respond to the Pcall16() or Slot\_marker(SN) command (Ready state). To be considered during the anticollision sequence, it must have received the Initiate() command and entered the Inventory state.

Table 4 shows the elements of a standard anticollision sequence. (See Figure 22 for an example.)

**Table 4. Standard anticollision sequence**

Step 1	Init:	Send Initiate(). – If no answer is detected, go to step1. – If only 1 answer is detected, select and access the SRI2K. After accessing the SRI2K, deselect the tag and go to step1. – If a collision (many answers) is detected, go to step2.
Step 2	Slot 0	Send Pcall16(). – If no answer or collision is detected, go to step3. – If 1 answer is detected, store the Chip_ID, Send Select() and go to step3.
Step 3	Slot 1	Send Slot_marker(1). – If no answer or collision is detected, go to step4. – If 1 answer is detected, store the Chip_ID, Send Select() and go to step4.
Step 4	Slot 2	Send Slot_marker(2). – If no answer or collision is detected, go to step5. – If 1 answer is detected, store the Chip_ID, Send Select() and go to step5.
Step N	Slop N	Send Slot_marker(3 up to 14)... – If no answer or collision is detected, go to stepN+1. – If 1 answer is detected, store the Chip_ID, Send Select() and go to stepN+1.
Step 17	Slot 15	Send Slot_marker(15). – If no answer or collision is detected, go to step18. – If 1 answer is detected, store the Chip_ID, Send Select() and go to step18.
Step 18		All the slots have been generated and the Chip_ID values should be stored into the reader memory. Issue the Select(Chip_ID) command and access each identified SRI2K one by one. After accessing each SRI2K, switch them into Deselected or Deactivated state, depending on the application needs. – If collisions were detected between Step2 and Step17, go to Step2. – If no collision was detected between Step2 and Step17, go to Step1.

After each Slot\_marker() command, there may be several, one or no answers from the SRI2K devices. The reader must handle all the cases and store all the Chip\_IDs, correctly decoded. At the end of the anticollision sequence, after Slot\_marker(15), the reader can start working with one SRI2K by issuing a Select() command containing the desired Chip\_ID. If a collision is detected during the anticollision sequence, the reader has to generate a new sequence in order to identify all unidentified SRI2K devices in the field. The anticollision sequence can stop when all SRI2K devices have been identified.



Figure 22. Example of an anticollision sequence

Command	Tag 1 Chip_ID	Tag 2 Chip_ID	Tag 3 Chip_ID	Tag 4 Chip_ID	Tag 5 Chip_ID	Tag 6 Chip_ID	Tag 7 Chip_ID	Tag 8 Chip_ID	Comments
READY State	28h	75h	40h	01h	02h	FEh	A9h	7Ch	Each tag gets a random Chip_ID
INITIATE ()	40h	13h	3Fh	4Ah	50h	48h	52h	7Ch	Each tag get a new random Chip_ID. All tags answer: collisions
PCALL16()	45h	12h	30h	43h	55h	43h	53h	73h	All CHIP_SLOT_NUMBERS get a new random value Slot0: only one answer
SELECT(30h)			30h						Tag3 is identified
SLOT_MARKER(1)									Slot1: no answer
SLOT_MARKER(2)		12h							Slot2: only one answer
SELECT(12h)		12h							Tag2 is identified
SLOT_MARKER(3)				43h		43h	53h	73h	Slot3: collisions
SLOT_MARKER(4)									Slot4: no answer
SLOT_MARKER(5)	45h				55h				Slot5: collisions
SLOT_MARKER(6)									Slot6: no answer
SLOT_MARKER(N)									SlotN: no answer
SLOT_MARKER(F)									SlotF: no answer
PCALL16()	40h			41h	53h	42h	50h	74h	All CHIP_SLOT_NUMBERS get a new random value Slot0: collisions
SLOT_MARKER(1)	40h			41h			50h		Slot1: only one answer
SELECT(41h)				41h					Tag4 is identified
SLOT_MARKER(2)						42h			Slot2: only one answer
SELECT(42h)						42h			Tag6 is identified
SLOT_MARKER(3)					53h				Slot3: only one answer
SELECT(53h)					53h				Tag5 is identified
SLOT_MARKER(4)								74h	Slot4: only one answer
SELECT(74h)								74h	Tag8 is identified
SLOT_MARKER(N)									SlotN: no answer
PCALL16()	41h						50h		All CHIP_SLOT_NUMBERS get a new random value Slot0: only one answer
SELECT(50h)							50h		Tag7 is identified
SLOT_MARKER(1)	41h								Slot1: only one answer but already found for tag4
SLOT_MARKER(N)									SlotN: no answer
PCALL16()	43h								All CHIP_SLOT_NUMBERS get a new random value Slot0: only one answer
SLOT_MARKER(3)	43h								Slot3: only one answer
SELECT(43h)								43h	Tag1 is identified
									All tags are identified

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## 8 SRI2K commands

See the paragraphs below for a detailed description of the commands available on the SRI2K. The commands and their hexadecimal codes are summarized in [Table 5](#). A brief is given in [Appendix B](#).

**Table 5. Command code**

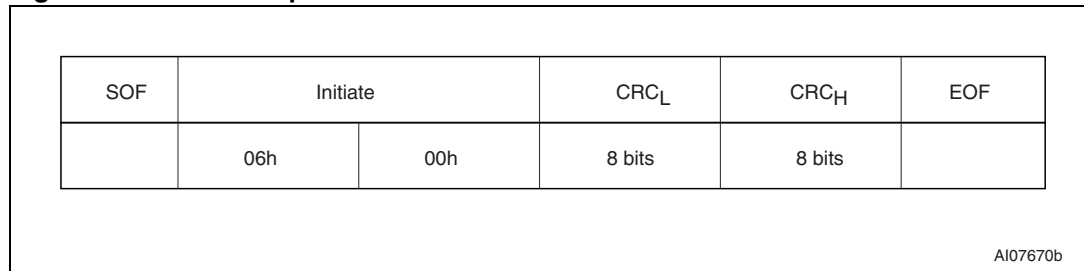
Hexadecimal code	Command
06h-00h	Initiate()
06h-04h	Pcall16()
x6h	Slot_marker (SN)
08h	Read_block(Addr)
09h	Write_block(Addr, Data)
0Bh	Get_UID()
0Ch	Reset_to_inventory
0Eh	Select(Chip_ID)
0Fh	Completion()

## 8.1 Initiate() command

Command code = 06h - 00h

Initiate() is used to initiate the anticollision sequence of the SRI2K. On receiving the Initiate() command, all SRI2K devices in Ready state switch to Inventory state, set a new 8-bit Chip\_ID random value, and return their Chip\_ID value. This command is useful when only one SRI2K in Ready state is present in the reader field range. It speeds up the Chip\_ID search process. The Chip\_slot\_number is not used during Initiate() command access.

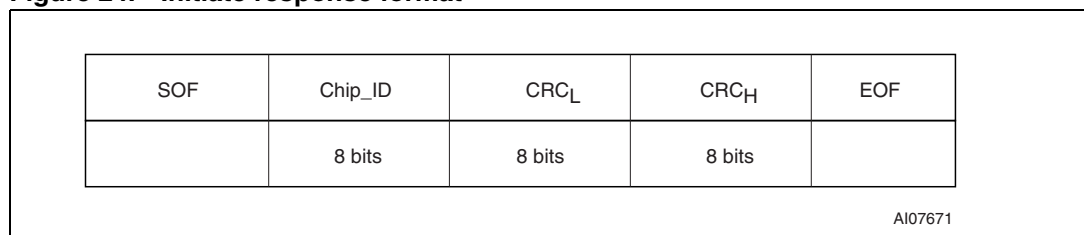
Figure 23. Initiate request format



Request parameter:

- No parameter

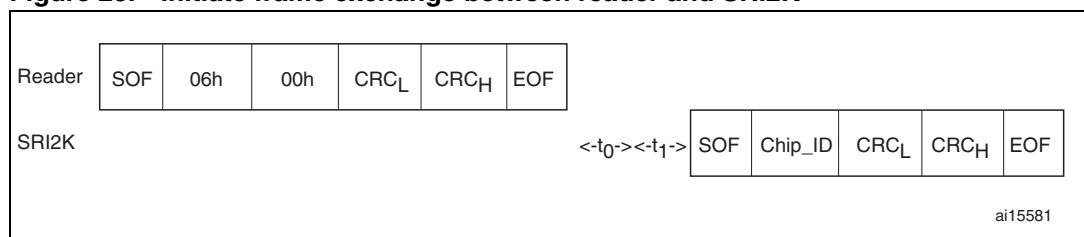
Figure 24. Initiate response format



Response parameter:

- Chip\_ID of the SRI2K

Figure 25. Initiate frame exchange between reader and SRI2K



### 8.2 Pcall16() command

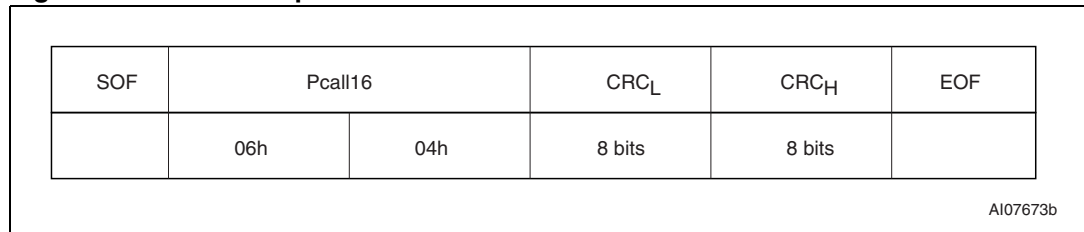
Command code = 06h - 04h

The SRI2K must be in Inventory state to interpret the Pcall16() command.

On receiving the Pcall16() command, the SRI2K first generates a new random Chip\_slot\_number value (in the 4 least significant bits of the Chip\_ID). Chip\_slot\_number can take on a value between 0 and 15 (1111<sub>b</sub>). The value is retained until a new Pcall16() or Initiate() command is issued, or until the SRI2K is powered off. The new Chip\_slot\_number value is then compared with the value 0000<sub>b</sub>. If they match, the SRI2K returns its Chip\_ID value. If not, the SRI2K does not send any response.

The Pcall16() command, used together with the Slot\_marker() command, allows the reader to search for all the Chip\_IDs when there are more than one SRI2K device in Inventory state present in the reader field range.

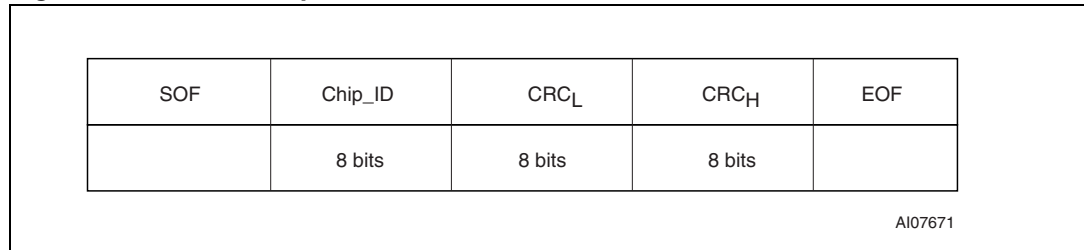
Figure 26. Pcall16 request format



Request parameter:

- No parameter

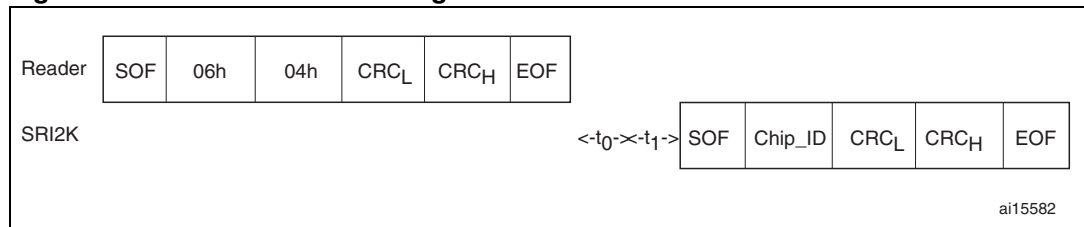
Figure 27. Pcall16 response format



Response parameter:

- Chip\_ID of the SRI2K

Figure 28. Pcall16 frame exchange between reader and SRI2K



### 8.3 Slot\_marker(SN) command

Command code = x6h

The SRI2K must be in Inventory state to interpret the Slot\_marker(SN) command.

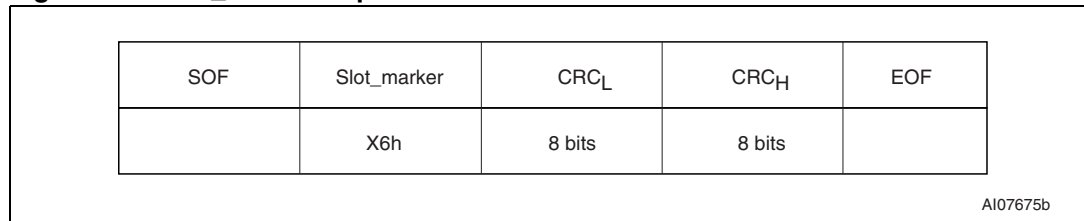
The Slot\_marker byte code is divided into two parts:

- b<sub>3</sub> to b<sub>0</sub>: 4-bit command code with fixed value 6.
- b<sub>7</sub> to b<sub>4</sub>: 4 bits known as the Slot\_number (SN). They assume a value between 1 and 15. The value 0 is reserved by the Pcall16() command.

On receiving the Slot\_marker() command, the SRI2K compares its Chip\_slot\_number value with the Slot\_number value given in the command code. If they match, the SRI2K returns its Chip\_ID value. If not, the SRI2K does not send any response.

The Slot\_marker() command, used together with the Pcall16() command, allows the reader to search for all the Chip\_IDs when there are more than one SRI2K device in Inventory state present in the reader field range.

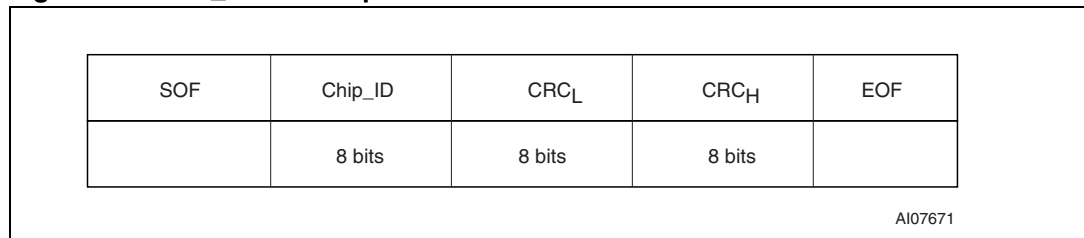
**Figure 29. Slot\_marker request format**



Request parameter:

- x: Slot number

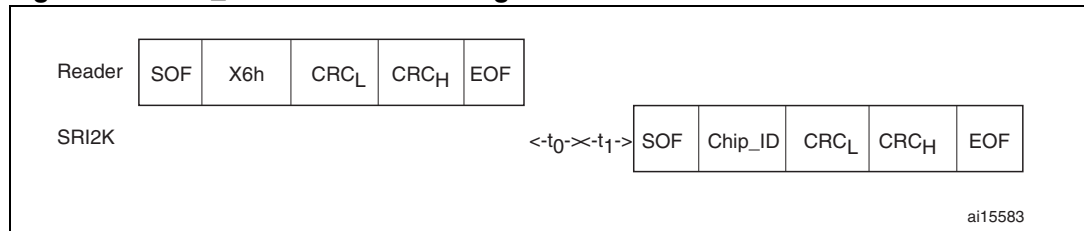
**Figure 30. Slot\_marker response format**



Response parameters:

- Chip\_ID of the SRI2K

**Figure 31. Slot\_marker frame exchange between reader and SRI2K**

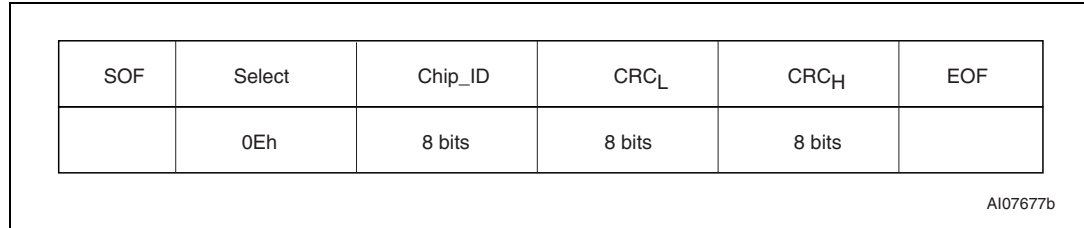


### 8.4 Select(Chip\_ID) command

Command code = 0Eh

The Select() command allows the SRI2K to enter the Selected state. Until this command is issued, the SRI2K will not accept any other command, except for Initiate(), Pcall16() and Slot\_marker(). The Select() command returns the 8 bits of the Chip\_ID value. An SRI2K in Selected state, that receives a Select() command with a Chip\_ID that does not match its own is automatically switched to Deselected state.

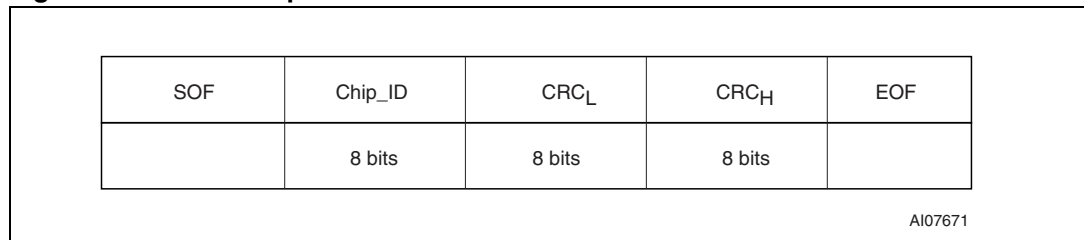
**Figure 32. Select request format**



Request parameter:

- 8-bit Chip\_ID stored during the anticollision sequence

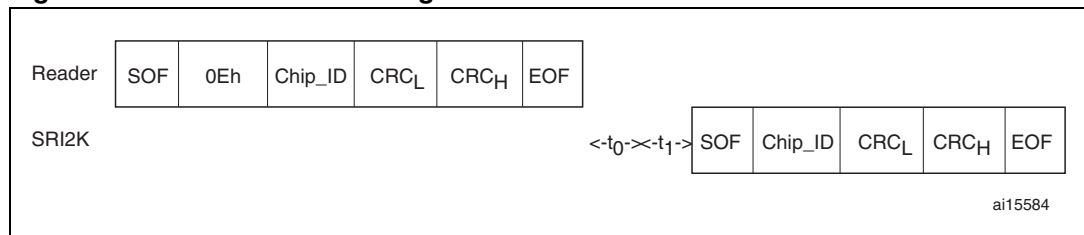
**Figure 33. Select response format**



Response parameters:

- Chip\_ID of the selected tag. Must be equal to the transmitted Chip\_ID

**Figure 34. Select frame exchange between reader and SRI2K**



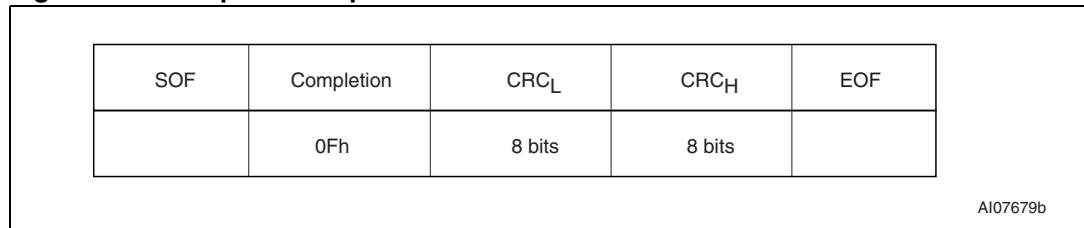
## 8.5 Completion() command

Command code = 0Fh

On receiving the Completion() command, an SRI2K in Selected state switches to Deactivated state and stops decoding any new commands. The SRI2K is then locked in this state until a complete reset (tag out of the field range). A new SRI2K can thus be accessed through a Select() command without having to remove the previous one from the field. The Completion() command does not generate a response.

All SRI2K devices not in Selected state ignore the Completion() command.

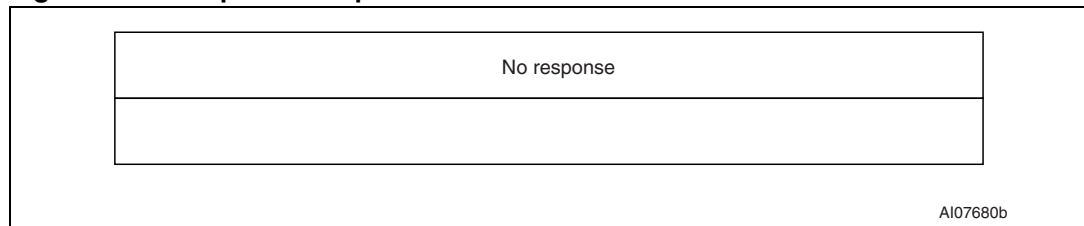
**Figure 35. Completion request format**



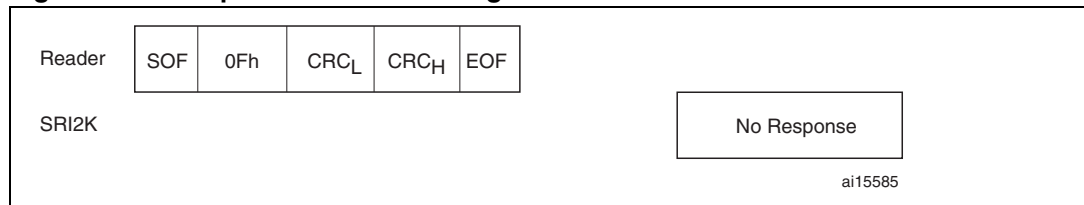
Request parameters:

- No parameter

**Figure 36. Completion response format**



**Figure 37. Completion frame exchange between reader and SRI2K**



## 8.6 Reset\_to\_inventory() command

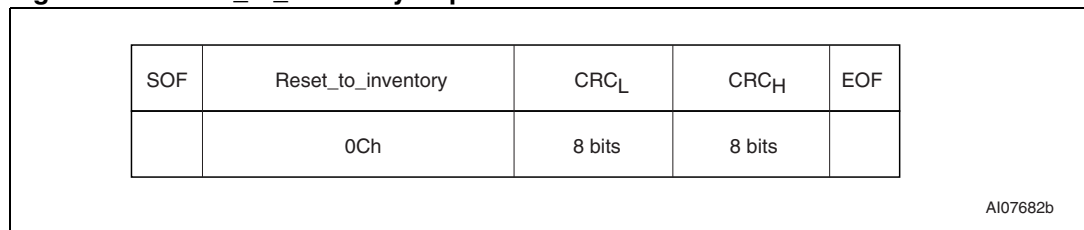
Command code = 0Ch

On receiving the Reset\_to\_inventory() command, all SRI2K devices in Selected state revert to Inventory state. The concerned SRI2K devices are thus resubmitted to the anticollision sequence. This command is useful when two SRI2K devices with the same 8-bit Chip\_ID happen to be in Selected state at the same time. Forcing them to go through the anticollision sequence again allows the reader to generate new Pcall16() commands and so, to set new random Chip\_IDs.

The Reset\_to\_inventory() command does not generate a response.

All SRI2K devices that are not in Selected state ignore the Reset\_to\_inventory() command.

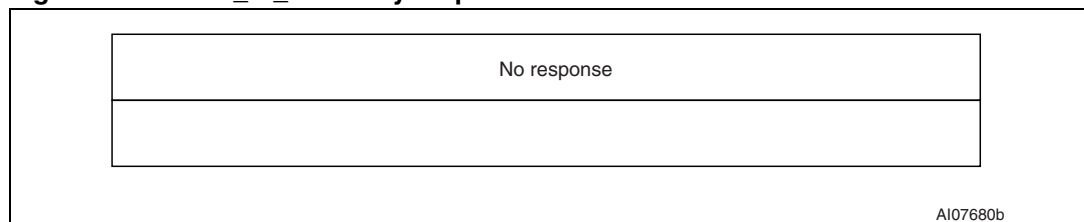
**Figure 38. Reset\_to\_inventory request format**



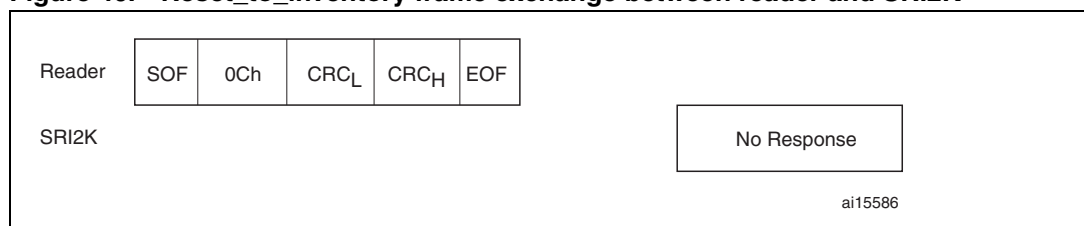
Request parameter:

- No parameter

**Figure 39. Reset\_to\_inventory response format**



**Figure 40. Reset\_to\_inventory frame exchange between reader and SRI2K**





## 8.7 Read\_block(Addr) command

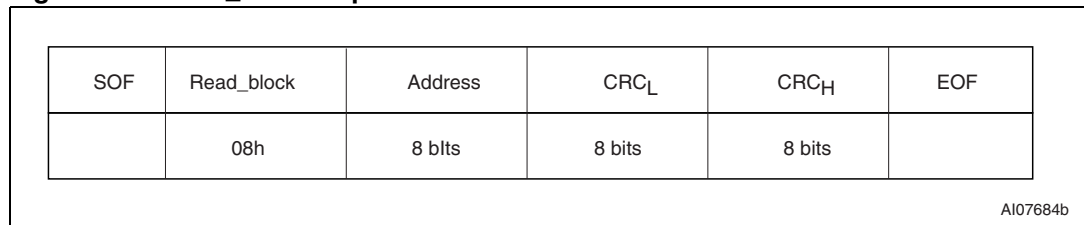
Command code = 08h

On receiving the Read\_block command, the SRI2K reads the desired block and returns the 4 data bytes contained in the block. Data bytes are transmitted with the least significant byte first and each byte is transmitted with the least significant bit first.

The address byte gives access to the 64 blocks of the SRI2K (addresses 0 to 63). Read\_block commands issued with a block address from 64 to 127 will generate a non-significative answer. Read\_block commands issued with a block address above 127 will not be interpreted and the SRI2K will not return any response, except for the System area located at address 255.

The SRI2K must have received a Select() command and be switched to Selected state before any Read\_block() command can be accepted. All Read\_block() commands sent to the SRI2K before a Select() command is issued are ignored.

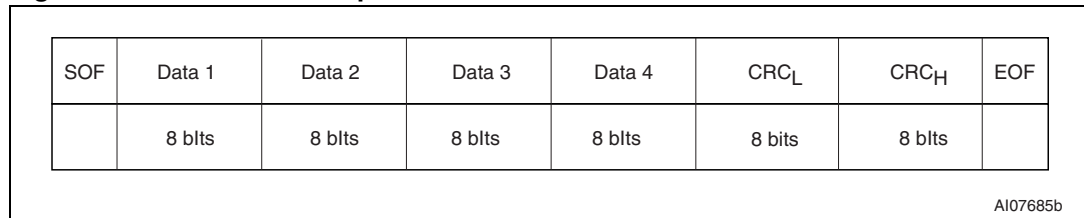
**Figure 41. Read\_block request format**



Request parameter:

- Address: block addresses from 0 to 63, or 255

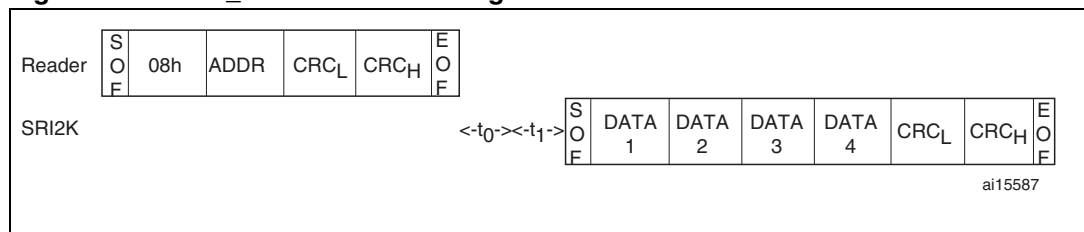
**Figure 42. Read\_block response format**



Response parameters:

- Data 1: Less significant data byte
- Data 2: Data byte
- Data 3: Data byte
- Data 4: Most significant data byte

**Figure 43. Read\_block frame exchange between reader and SRI2K**



## 8.8 Write\_block (Addr, Data) command

Command code = 09h

On receiving the Write\_block command, the SRI2K writes the 4 bytes contained in the command to the addressed block, provided that the block is available and not write-protected. Data bytes are transmitted with the least significant byte first, and each byte is transmitted with the least significant bit first.

The address byte gives access to the 64 blocks of the SRI2K (addresses 0 to 63). Write\_block commands issued with a block address above 63 will not be interpreted and the SRI2K will not return any response, except for the System area located at address 255.

The result of the Write\_block command is submitted to the addressed block. See the following Figures for a complete description of the Write\_block command:

- [Figure 12: Resettable OTP area \(addresses 0 to 4\).](#)
- [Figure 15: Binary counter \(addresses 5 to 6\).](#)
- [Figure 17: EEPROM \(addresses 7 to 63\).](#)

The Write\_block command does not give rise to a response from the SRI2K. The reader must check after the programming time,  $t_{W}$ , that the data was correctly programmed. The SRI2K must have received a Select() command and be switched to Selected state before any Write\_block command can be accepted. All Write\_block commands sent to the SRI2K before a Select() command is issued, are ignored.

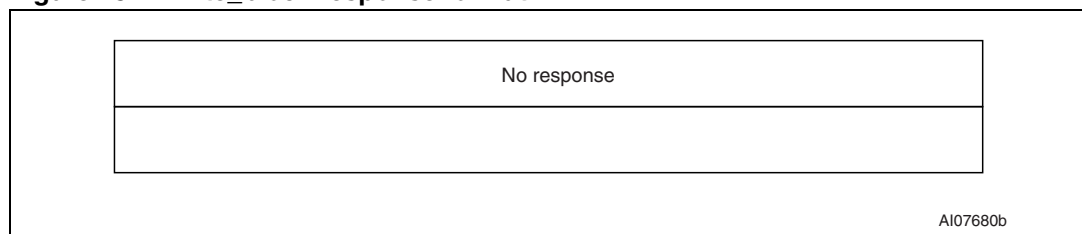
**Figure 44. Write\_block request format**

SOF	Write_block	Address	Data 1	Data 2	Data 3	Data 4	CRC <sub>L</sub>	CRC <sub>H</sub>	EOF
	09h	8 blts	8 blts	8 blts	8 blts	8 blts	8 bits	8 bits	

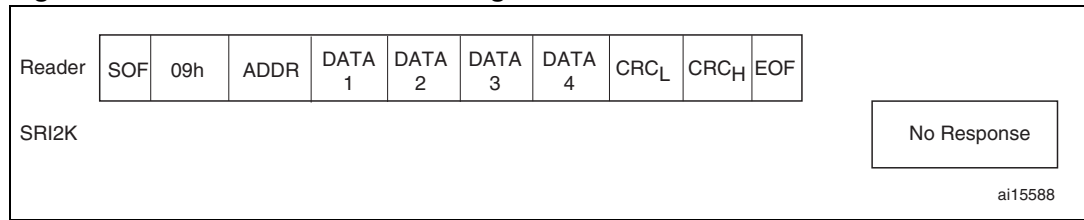
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- Request parameters:
- Address: block addresses from 0 to 63, or 255
- Data 1: Less significant data byte
- Data 2: Data byte
- Data 3: Data byte
- Data 4: Most significant data byte.

**Figure 45. Write\_block response format**



**Figure 46. Write\_block frame exchange between reader and SRI2K**



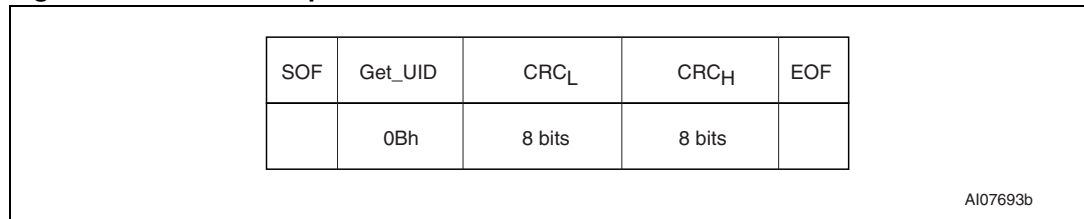
## 8.9 Get\_UID() command

Command code = 0Bh

On receiving the Get\_UID command, the SRI2K returns its 8 UID bytes. UID bytes are transmitted with the least significant byte first, and each byte is transmitted with the least significant bit first.

The SRI2K must have received a Select() command and be switched to Selected state before any Get\_UID() command can be accepted. All Get\_UID() commands sent to the SRI2K before a Select() command is issued, are ignored.

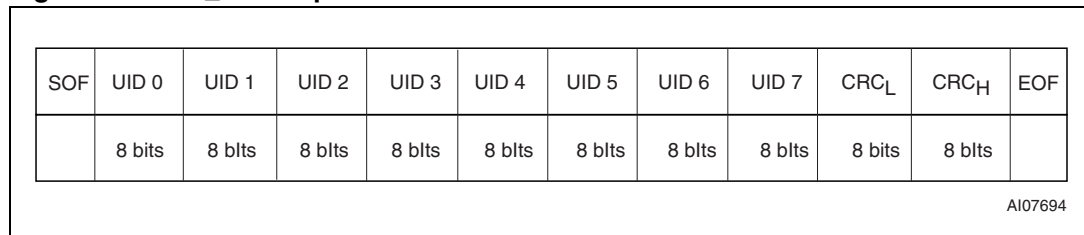
**Figure 47. Get\_UID request format**



Request parameter:

- No parameter

**Figure 48. Get\_UID response format**



Response parameters:

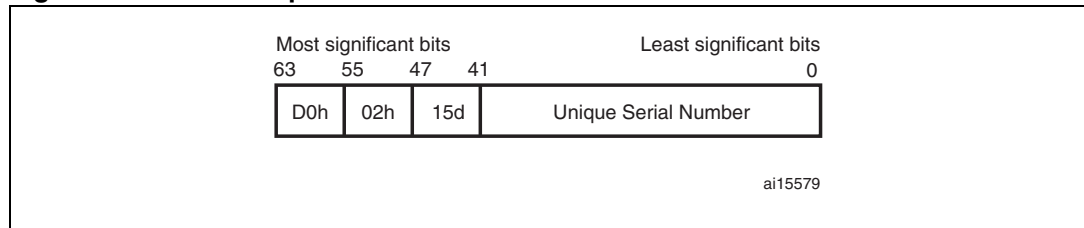
- UID 0: Less significant UID byte
- UID 1 to UID 6: UID bytes
- UID 7: Most significant UID byte.

### Unique identifier (UID)

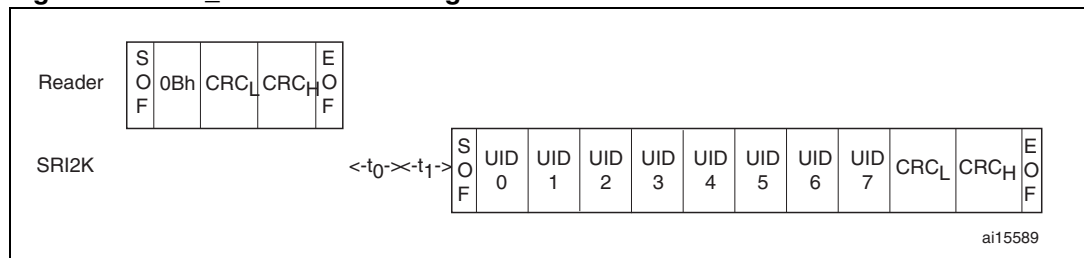
Members of the SRI2K family are uniquely identified by a 64-bit unique identifier (UID). This is used for addressing each SRI2K device uniquely after the anticollision loop. The UID complies with ISO/IEC 15963 and ISO/IEC 7816-6. It is a read-only code, and comprises (as summarized in *Figure 49*):

- an 8-bit prefix, with the most significant bits set to D0h
- an 8-bit IC manufacturer code (ISO/IEC 7816-6/AM1) set to 02h (for STMicroelectronics)
- a 6-bit IC code set to 00 1111b = 15d for SRI2K
- a 42-bit unique serial number

**Figure 49. 64-bit unique identifier of the SRI2K**



**Figure 50. Get\_UID frame exchange between reader and SRI2K**



## 8.10 Power-on state

After power-on, the SRI2K is in the following state:

- It is in the low-power state.
- It is in Ready state.
- It shows highest impedance with respect to the reader antenna field.
- It will not respond to any command except Initiate().

## 9 Maximum rating

Stressing the device above the rating listed in the absolute maximum ratings table may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability. Refer also to the STMicroelectronics SURE Program and other relevant quality documents.

**Table 6. Absolute maximum ratings**

Symbol	Parameter		Min.	Max.	Unit
$T_{STG}$ , $t_{STG}$	Storage conditions	Wafer (kept in its antistatic bag)	15	25	°C
				23	months
$I_{CC}$	Supply current on AC0 / AC1		-20	20	mA
$V_{MAX}$	Input voltage on AC0 / AC1		-7	7	V
$V_{ESD}$	Electrostatic discharge voltage <sup>(1)</sup>	Machine model	-100	100	V
		Human body model	-1000	1000	V

1. Mil. Std. 883 - Method 3015

## 10 DC and ac parameters

**Table 7. Operating conditions**

Symbol	Parameter	Min.	Max.	Unit
T <sub>A</sub>	Ambient operating temperature	-20	85	°C

**Table 8. DC characteristics**

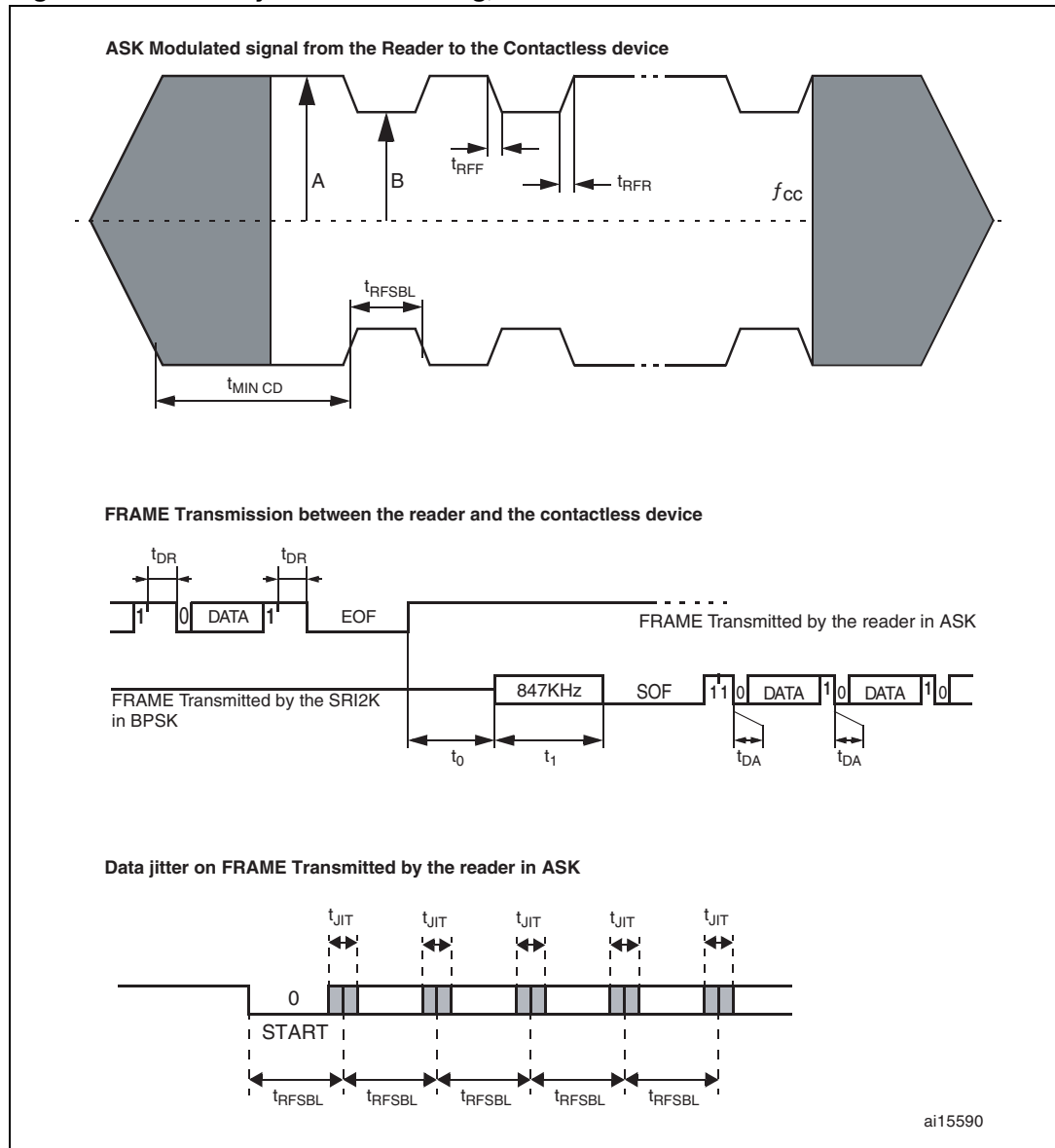
Symbol	Parameter	Condition	Min	Typ	Max	Unit
V <sub>CC</sub>	Regulated voltage		2.5		3.5	V
I <sub>CC</sub>	Supply current (active in read)	V <sub>CC</sub> = 3.0 V			100	μA
I <sub>CC</sub>	Supply current (active in write)	V <sub>CC</sub> = 3.0 V			250	μA
V <sub>RET</sub>	Retromodulation induced voltage	ISO 10373-6	20			mV
C <sub>TUN</sub>	Internal tuning capacitor	13.56 MHz		64		pF

**Table 9. AC characteristics<sup>(1)</sup>**

Symbol	Parameter	Condition	Min	Max	Unit
f <sub>CC</sub>	External RF signal frequency		13.553	13.567	MHz
MI <sub>CARRIER</sub>	Carrier modulation index	MI=(A-B)/(A+B)	8	14	%
t <sub>RFR</sub> , t <sub>RFF</sub>	10% Rise and Fall times		0.8	2.5	μs
t <sub>RFSBL</sub>	Minimum pulse width for Start bit	ETU = 128/f <sub>CC</sub>	9.44		μs
t <sub>JIT</sub>	ASK modulation data jitter	Coupler to SRI2K	-2	+2	μs
t <sub>MIN CD</sub>	Minimum time from carrier generation to first data		5		ms
f <sub>S</sub>	Subcarrier frequency	f <sub>CC</sub> /16	847.5		kHz
t <sub>0</sub>	Antenna reversal delay	128/f <sub>S</sub>	151		μs
t <sub>1</sub>	Synchronization delay	128/f <sub>S</sub>	151		μs
t <sub>2</sub>	Answer to new request delay	14 ETU	132		μs
t <sub>DR</sub>	Time between request characters	Coupler to SRI2K	0	57	μs
t <sub>DA</sub>	Time between answer characters	SRI2K to coupler	0		μs
t <sub>W</sub>	Programming time for write	With no auto-erase cycle (OTP)		3	ms
		With auto-erase cycle (EEPROM)		5	ms
		Binary counter decrement		7	ms

1. All timing measurements were performed on a reference antenna with the following characteristics:  
 External size: 75 mm x 48 mm  
 Number of turns: 3  
 Width of conductor: 1 mm  
 Space between 2 conductors: 0.4 mm  
 Value of the coil: 1.4 μH  
 Tuning Frequency: 14.4 MHz.

Figure 51. SRI2K synchronous timing, transmit and receive



# 11 Part numbering

**Table 10. Ordering information scheme**

Example:	SRI2K	-	W4	/1GE
<b>Device type</b>				
SRI2K				
<b>Package</b>				
W4 = 180 μm ± 15 μm unsawn wafer				
SBN18 = 180 μm ± 15 μm bumped and sawn wafer on 8-inch frame				
<b>Customer code</b>				
1GE = generic product				
xxx = customer code after personalization				

*Note:* Devices are shipped from the factory with the memory content bits erased to 1.  
 For a list of available options (speed, package, etc.) or for further information on any aspect of this device, please contact your nearest ST sales office.



## Appendix A ISO-14443 Type B CRC calculation

```

#include <stdio.h>
#include <stdlib.h>
#include <string.h>
#include <ctype.h>
#define BYTE unsigned char
#define USHORT unsigned short

unsigned short UpdateCrc(BYTE ch, USHORT *lpwCrc)
{
    ch = (ch^(BYTE)((*lpwCrc) & 0x00FF));
    ch = (ch^(ch<<4));
    *lpwCrc = (*lpwCrc >> 8) ^ ((USHORT)ch <<
8) ^ ((USHORT)ch<<3) ^ ((USHORT)ch>>4);
    return(*lpwCrc);
}

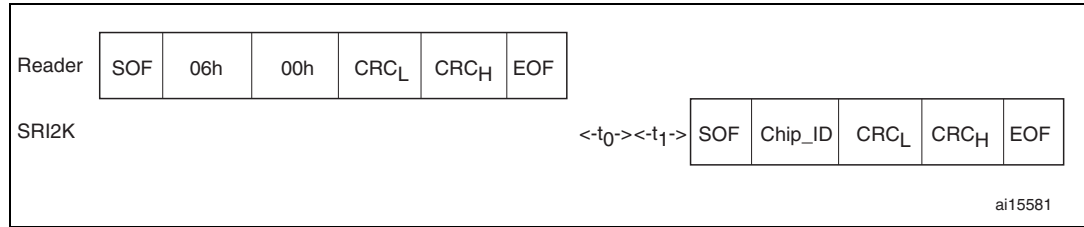
void ComputeCrc(char *Data, int Length, BYTE *TransmitFirst, BYTE
*TransmitSecond)
{
    BYTE chBlock; USHORTt wCrc;
    wCrc = 0xFFFF; // ISO 3309
    do
    {
        chBlock = *Data++;
        UpdateCrc(chBlock, &wCrc);
    } while (--Length);
    wCrc = ~wCrc; // ISO 3309
    *TransmitFirst = (BYTE) (wCrc & 0xFF);
    *TransmitSecond = (BYTE) ((wCrc >> 8) & 0xFF);
    return;
}

int main(void)
{
    BYTE BuffCRC_B[10] = {0x0A, 0x12, 0x34, 0x56}, First, Second, i;
    printf("Crc-16 G(x) = x^16 + x^12 + x^5 + 1");
    printf("CRC_B of [ ");
    for(i=0; i<4; i++)
        printf("%02X ",BuffCRC_B[i]);
    ComputeCrc(BuffCRC_B, 4, &First, &Second);
    printf("] Transmitted: %02X then %02X.", First, Second);
    return(0);
}

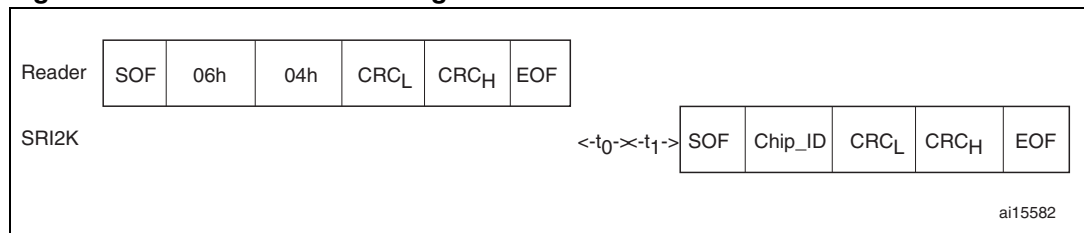
```

## Appendix B SRI2K command summary

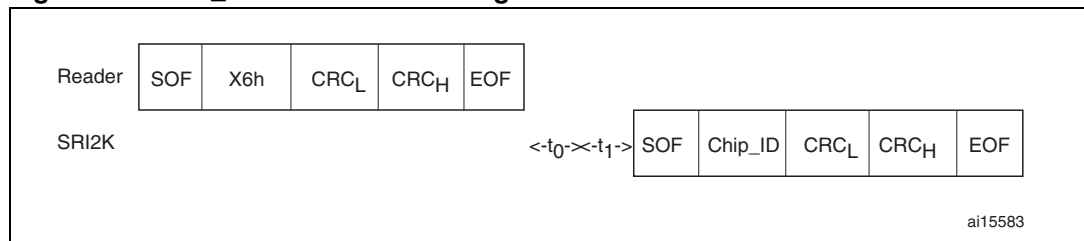
**Figure 52. Initiate frame exchange between reader and SRI2K**



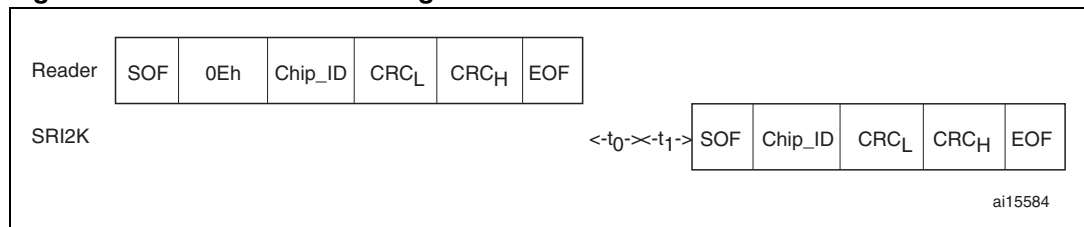
**Figure 53. Pcall16 frame exchange between reader and SRI2K**



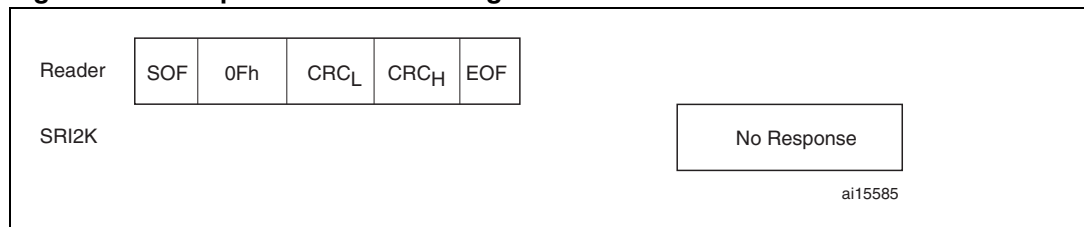
**Figure 54. Slot\_marker frame exchange between reader and SRI2K**



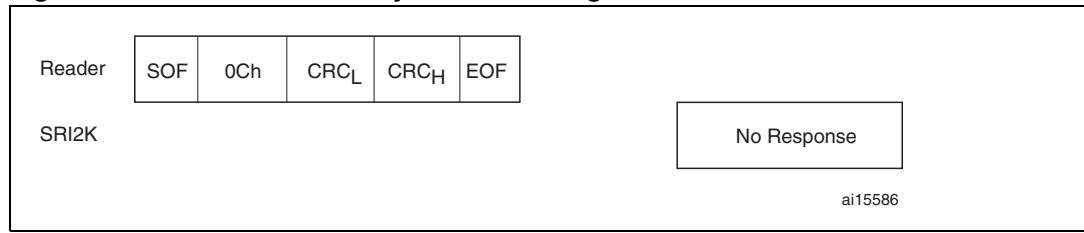
**Figure 55. Select frame exchange between reader and SRI2K**



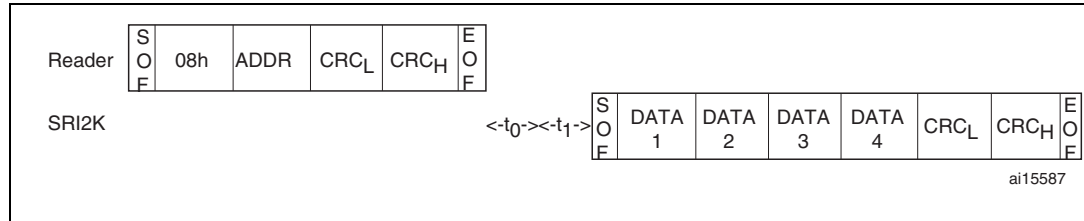
**Figure 56. Completion frame exchange between reader and SRI2K**



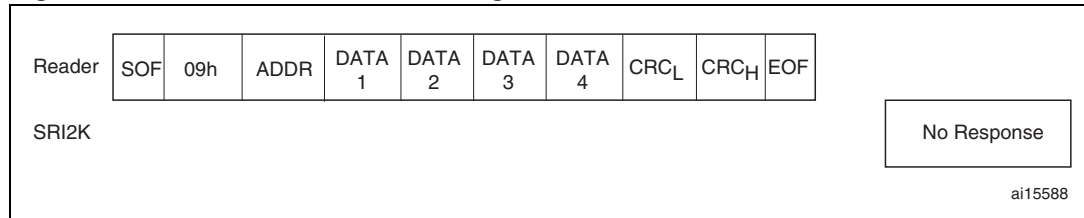
**Figure 57. Reset\_to\_inventory frame exchange between reader and SRI2K**



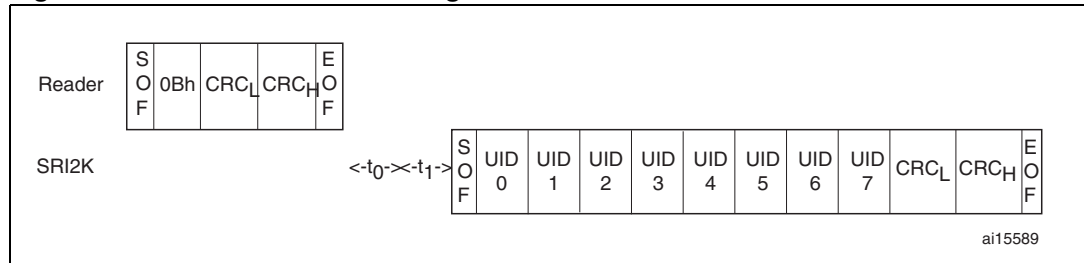
**Figure 58. Read\_block frame exchange between reader and SRI2K**



**Figure 59. Write\_block frame exchange between reader and SRI2K**



**Figure 60. Get\_UID frame exchange between reader and SRI2K**



## 12 Revision history

**Table 11. Document revision history**

Date	Revision	Changes
01-Jun-2009	1	Initial release.
19-Oct-2009	2	Document promoted from Preliminary data to full datasheet status. <a href="#">Section 8.7: Read_block(Addr) command</a> specified.
09-Sep-2011	3	Process technology removed from <a href="#">Section 1: iDescription</a> . Updated disclaimer on last page.

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